

# 국외 공무여행 결과 보고서

- 중국 계림 -

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2017. 12.

기획조정연구부 권영현 연구실장  
지역도시연구부 임준홍 연구위원  
김원철 책임연구원



**충남연구원**  
ChungNam Institute

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## 1. 공무여행 개요

- 출장기간 : 2017년 12월 10일(일) - 13일(수), 3박4일
- 출장지역 : 중국 계림(Guilin)시 계림전자기술대학
- 출 장 자 : 권영현 연구실장, 임준홍 연구위원, 김원철 책임연구원

## 2. 공무여행 목적

- 중국 계림전자기술대학(Guilin University of Electronic Technology)과 공동연구, 인력교류, 등 연구 활성화를 위한과 양해각서(Memorandum of Understanding : MOU) 체결 (본원 지역도시연구부 및 중국 계림전자기술대학 건축교통공학과)
- 계림전자기술대학에서 개최한 국제세미나에서 충남 지역도시정책 방향 및 교통연구 주제 발표 요청

## 3. 주요 세부일정

Date	Time	Schedule
10(일)	07:00~10:00	공주 ⇒ 인천국제공항
	12:00~19:00	인천국제공항 ⇒ 상하이푸동공항 ⇒ 구이린국제공항 (중국남방항공, 상하이항공)
	20:00~	호텔
11(월)	10:00~12:00	MOU 및 세미나 발표 준비 등
	14:00~17:00	MOU 체결
	19:00~	호텔
12(화)	10:00~17:00	세미나 참석 및 주제 발표 - 발표1 : The Impact of Development of Naepo New Town on Neighboring Cities (임준홍) - 발표2 : Influence of In-Vehicle Real-Time Traffic Safety Warning Information on Driving Stability at Limited Signal Visibility Approach (김원철)
	19:00~	호텔
13(수)	08:40~16:00	구이린국제공항 ⇒ 상하이푸동공항 ⇒ 인천공항 (중국남방항공, 아시아나)
	17:00~20:00	인천국제공항 ⇒ 공주

#### 4. 공무여행 국가 개요

- 계림시(구이린)는 중국의 남쪽에 위치하며 계림을 기준으로 서쪽으로 류저우, 남쪽으로 라이빈, 우저우, 동쪽으로 허저우와 후난 성 융저우, 북쪽으로 후난 성 사오양과 접하고 베트남과 국경을 이루고 있음.
- 이곳에 거주하고 있는 주민은 약 495만명 정도인데 장족(약 85% 차지), 한족, 묘족, 모한족 등 다양한 민족으로 형성되어 있고, 명·청때 광서성으로 불리다가 1958년에 자치구로 성립되었음
- 해저에서 지각변동으로 육지가 된 카르스트 지형으로 '꾸이린산수갑천'이라는 명성으로 중국 10대 관광명승지 국제 관광도시, 국가지정 문화재 및 유적지가 109개소에 이르며 꾸이린산수를 찬미한 시, 불교, 조각상들이 많이 산재하고 있는 역사, 문화의 도시로 시내교통이 매우 편리하며 관광객들을 위해 다른 도시에서 쉽게 볼 수 없는 무료셔틀버스를 운행하고 있음



### **(1) The Impact of Development of Naepo New Town on Neighboring Cities**

# The impact of development of Naepo new town on neighboring cities

*Can you guess what it is?*

Jun-hong, Im

Naepo new town (100,000 residents/by 2020)

**Impact**

Naepo new town 15km Yesan  
Hongseong 6km

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## Contents

The impact of development of Naepo new town on neighboring cities

01. The background and objective of this study
02. Data and the method of analysis
03. Empirical results
04. Conclusion

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### 01\_ The background and objective of this study

#### 01\_1 The background

#### 2 reasons for developing the Naepo new town

- To move Chungnam provincial office into the border of Chungnam  
( from Daejeon to Chungnam )
- To realize balanced growth in Chungnam

decided to develop Naepo new town

[ Positive ]

Many people expected Hongseong and Yesan to grow together

➡

[ Negative ]

Naepo new town would have a negative effect on nearby cities

Balanced growth VS Donut phenomena

### 01\_ The background and objective of this study

#### 01\_1 The background

**Peoples' worries are becoming a reality**  
**As seen in the newspapers, experts are worrying**

내포신도시, 위기가 기뢰인가 1. [ 예산공동화, 홍성과 동함으로 해결될까? ] 예산발전위 해 유치한 도청... 지금은? - 연합뉴스 / 2012 지역신문 가침

Local governments made a task force team to minimize the negative effect

충청권 상생발전기대, 상생 아이디어 모으기 연찬회

- 충청권 도시 발전에 기여하기 위해 14개 시·군·자치단체가 공동 개최

주최 : 충청남도, 충청북도, 충청광역시, 충청특별자치도청

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▲ 내포신도시를 중심으로 분할구획별 거리지도

## 01. The background and objective of this study

### 01\_2 The purpose

To **empirically evaluate** how the development of Naepo **would affect** the nearby cities

How many people from nearby cities would move to Naepo?

What are the motives of the people to move there?  
\* Especially, the satisfaction with the residential environments will be analyzed

What the local governments have to do?

07/25

## 02

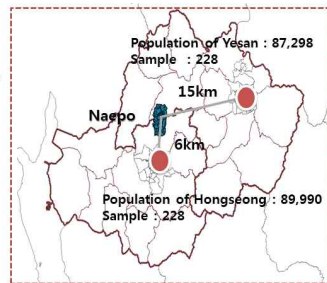
## Data and the method of analysis

## 02. Data and the method of analysis

### 02\_1 Data

- The empirical analysis : survey on 456 residents of Hongseong and Yesan

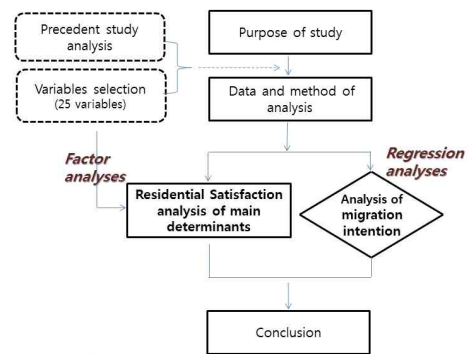
- The survey is asking
  - Intention of moving into Naepo
  - The degree of satisfaction with residential environments
  - Preferences on housing types



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## 02. Data and the method of analysis

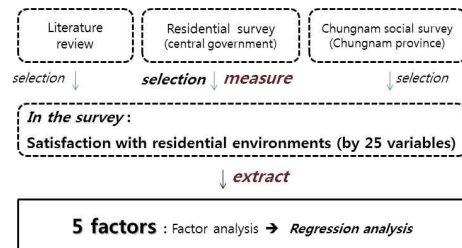
### 02\_2 Process of analysis



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## 02. Data and the method of analysis

### 02\_3 Input variables selection & factor extract

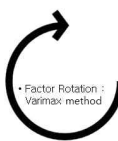


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## 02. Data and the method of analysis

### 02\_4 Factor analyses

	convenient facilities	environments	housing	Safety	Accessibility
Child care	.642	-.008	.014	.070	-.143
Welfare	.732	-.064	.229	.036	-.011
Culture facilities	.729	-.112	.072	.167	-.050
Medical service	.728	-.103	.310	.028	.175
Education	.729	-.048	.095	.123	-.047
Shopping	.674	-.071	.238	.038	.382
Shopping	.697	.004	.230	.023	.186
Public safety	-.111	.448	.025	.037	.171
Atmospheric environment	-.081	.802	.066	-.043	.185
Soil environment	-.082	.747	.014	.199	.073
Nature environment	-.143	.746	.009	.255	-.010
Water environment	.144	.729	.055	.234	-.037
Housing size	.090	.121	.698	.090	.122
Housing structure	.351	.014	.778	.132	.023
Housing facility	.437	-.026	.636	.169	.009
Neighborhood	.387	.101	.687	.207	.146
Fire safety	.061	.081	.050	.616	.062
Traffic safety	.086	.195	.133	.766	.073
Safety of building	.430	.142	.174	.463	.057
Public safety	.127	.241	.056	.432	.186
Disaster	-.013	.362	.196	.466	.207
Crime	-.045	.187	.084	.354	.437
Bus	.320	.039	-.081	.257	.635
Taxi	.480	-.047	.091	.153	.619
Commute time	-.195	.139	.146	-.072	.664
Eigenvalue	4.947	3.329	2.445	2.141	1.963
Variance(%)	19.8	13.3	9.8	8.0	7.9
cumulative variation(%)	19.8	33.1	42.9	51.9	59.7



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## 02. Data and the method of analysis

### 02\_5 Regression analysis: GLMM

- Regression analysis\_ GLMM (Generalized Linear Mixed Models)

To find the determinants of migration intention  
I used regression analyses, especially GLMM.  
Equation 1 is the usual regression equation for GLMM.

Response variable  $Y_i$ , fixed factor  $X_1, \dots, X_p$ , Variate factor  $U_1, \dots, U_p$

$$Y_i | U_1 \sim G(U_i, \phi_i)$$

$Y_i$  :  $n_i \times 1$  response,  $U_i = Q \times 1$  Variate vector,  $\phi_i$  = Scale of the distribution of  $G$

$$\begin{aligned} g(u) &= X_i \beta + Z_i U_i, \text{ ----- (Equation 1)} \\ U_i &\sim N(0, V) \end{aligned}$$

$X_i = n_i \times p$  Matrix model,  $\beta = p \times 1$  Coefficient vector,

$Z_i = n_i \times q$  Matrix model,  $U_i = q \times 1$  Variate vector,  $V = q \times q$  Variate vector

$$\times y_j = \alpha_0 + A_j \beta + C_j \gamma + \epsilon_j \text{ ----- (Equation 2)}$$

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## 03

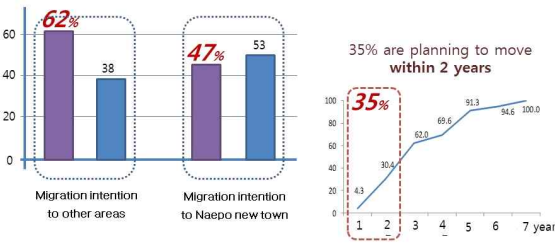
## Empirical results



### 03. Empirical Results

#### 03.1 How many people plan to move ?

- 62% of survey respondents **wanted to move** to other areas  
→ from that 47% are thinking about moving to the Naepo



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### 03. Empirical results

#### 03.2 Who would move ?

- Wage earners
- Short term residents
- Parents with pre-school - kid
- People in 20's and 30's

#### •• Migration Intention ••

		NO(%)	YES(%)	$\chi^2$
gender	Male	61.4	38.6	.084
	Female	62.7	37.3	
age	Age under 20	50.0	50.0	58.434**
	30's	37.6	62.4	
	40's	60.4	39.6	
	50's	70.9	29.1	
	Age over 60	87.4	12.6	
	Wage earners	40.7	59.3	
occupation	Private business (retailer, sales)	63.8	36.2	25.249**
	Housewives	66.7	33.3	
	Student, Etc.	65.0	35.0	
	Under 1million won	73.5	26.5	
	1mil-3million won	65.0	35.0	
	3mil-5million won	55.6	44.4	
income	Over 3million won	50.6	49.4	4.730

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### 03. Empirical results

#### 03.3 Why they want to move ?

- Which **residential environments** are so **unsatisfactory** to cause the residents to move out

< Influential Factors on residential satisfaction >				< Influential Factors on migration intention >			
Model Term	Coefficient	Std. Error	t	Model Term	Coefficient	Std. Error	t
Intercept	3.400	0.184	18.503***	Intercept	1.329	0.835	1.592
convenient facilities	0.295	0.029	10.246***	convenient facilities	0.472	0.129	3.654***
environments	0.187	0.030	6.251	environments	0.081	0.120	0.678
housing	0.290	0.023	12.514***	housing	0.243	0.113	2.142**
safety	0.192	0.024	8.113***	safety	0.324	0.117	2.760***
accessibility	0.101	0.023	4.346***	accessibility	0.254	0.114	2.234**
Statistics Bayesian = 710.312 / Residual Estimate = 0.227*** Corrected Model F=40.6359=0.000 / Probabilty distributon : normal Link function : identity				Statistics Bayesian = 2.143.356 Accuracy = 73.9% Corrected Model F=3.762*** Probability distribution : Binomial Link function : Logit			

\* Dependent variable : residential environment satisfaction(Likert scale)

\* Dependent variable : Migration intention (Yes : 0, No 1)

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### 03. Empirical results

#### 03.3 Why they want to move ?

- Relationship between residential satisfaction and migration intention.

Degree of migration intention



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## 04

### Conclusion

### 04. Conclusion

The largest development **project** **To realize** a balanced growth in Chungnam

#### • What do you think? •

The results of the analysis

Migration intention 47% *People that are thinking about moving to the Naepo*

- Recently people are **reserving to move** into Naepo new town apartments
- The 60% of the apartment buyers are from Hongseong and Yesan

People with intention to move People in 20' & 30' *The younger are leaving*

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### 04. Conclusion



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### 04. Conclusion

#### How can we reduce the negative effect ?

##### Urban regeneration

- Hongseong and Yesan : Residential environments *have to be improved.*
  - ✓ convenient facilities
  - ✓ Safety
  - ✓ Housing

- Local governments : Focus on **urban regeneration** rather than urban development.

##### The role of local governments

Naepo development → **Prevention** of donut phenomena

- The purpose of Naepo development was **balanced growth** in Chungnam  
→ Therefore, we must make **action plans** to grow together.

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특화 개념

협의체 아이디어

특화 기본컨셉

특화 실천전략

안전한 오픈스트리트(open streets) 조성

1 open streets

자율주행 셔틀

단기 : 순환버스 노선 및 디자인/순환버스/순환버스 정류장/안전차 휴게공간, 이동차 휴게센터 등

중장기 : 자율주행 셔틀 운행

① - - - - - ALT1 - 중심지대중형

② - - - - - ALT2 - 방사형

③ - - - - - ALT3 - 가점연결형

자전거도로

차원이 다른 자전거 도로

설치한 자전거 시설/자전거 주차장

보행중심/ 세그웨이 중심

차원이 다른 세그웨이 중심의 대포신도시

내로 지역 SNS 구축

내로 신도시 지역 SNS 특성과 최근 커뮤니티 공간에 온라인을 이용한 지역 커뮤니티 강화

내로 마을책사 운영

지역에 마을책사 운영

지역에 마을책사 운영을 위한 주민주도-행정-전문가 결합체

내로 마을책사 운영

안전한 오픈스트리트(open streets) 조성

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디자인가로

도로의 여유공간을 활용하여 디자인특화를 통한 특색있는 가로 연출

도로변 체험 놀이터

도로변(어린이공원) 체험 놀이터 조성

노천카페

도로변 여유로운 휴게공간과 휴식 제공

프리마켓(중심상점가)

지역 예술가/주민에게는 참여 활동, 방문객들에게는 새로운 볼거리 제공

내로 상생도서관 네트워크 구축

도서관 네트워크

내로도서관 - 원고-아름내 직문도서관 - 가리마도서관 등 특화특성 확립 강화

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도로변 체험놀이터

1 open streets

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1 open streets

특화 개념

협의체 아이디어

특화 기본컨셉

특화 실천전략

노천카페

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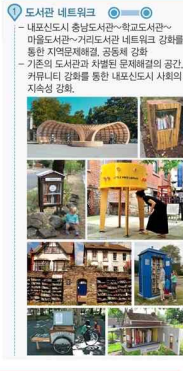
프리마켓(중심상점가) 1 open streets



프리마켓(중심상점가) 1 open streets

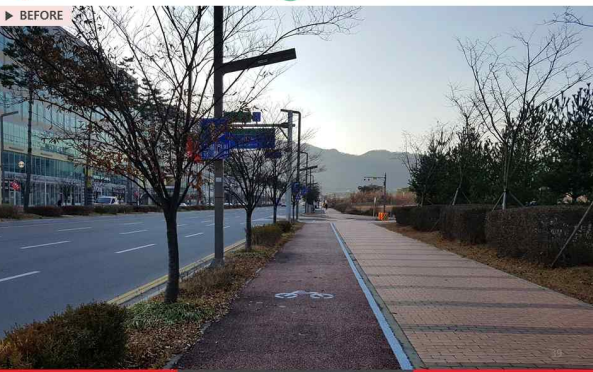


내포 상상도서관 네트워크 구축



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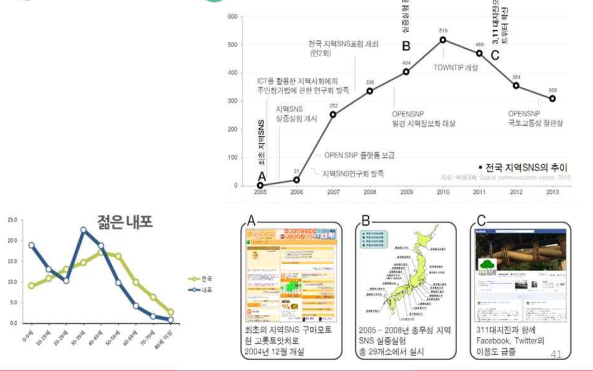
내포 상상도서관 네트워크 구축 2 내포 상상도서관



내포 상상도서관 네트워크 구축 2 내포 상상도서관



버튼업 내포SNS 구축 3 내포 SNS



버튼업 내포SNS 구축 3 내포 SNS



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## (2) Influence of In-Vehicle Real-Time Traffic Safety Warning Information on Driving Stability at Limited Signal Visibility Approach

### Influence of In-Vehicle Real-Time Traffic Safety Warning Information on Driving Stability at Limited Signal Visibility Approach: Use of Ordered Probit Model

Wonchul Kim, Ph.D  
ChungNam Institute

#### Contents

1. Introduction
2. Backgrounds
3. Data Collection
4. Utility of In-vehicle RTSWI
5. Driving Stability Risk Model Incorporating Short-Term Memory
6. Conclusions

#### Introduction

##### 1 Preface

- Cause of Traffic Accident
  - Interaction of extraordinary geometry, driver error, and vehicle problem
  - Accident frequency to be 52% higher at sites with sight distance restrictions due to vertical curvature than at control sites - TRB (1987)
- Road safety strategies
  - Generally, 3E (Education, Enforcement, Engineering)
  - Recently, applications of Intelligent Transportation System
- Smart 2-miles Hiroshima ITS project
  - Commenced in 2006
  - Improving traffic safety at signalized intersection
  - Provision of In-vehicle Real-time Traffic Safety Warning Information (RTSWI)

#### Introduction

##### 2 Purpose of Study

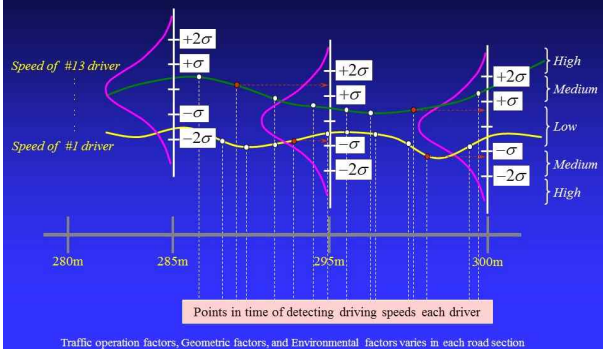
- Evaluating the effectiveness of In-vehicle RTSWI
  - Driving Stability Risk Model
  - Utility of the in-vehicle RTSWI incorporating driver's short-term memory
- Our research hypothesis
  - In-vehicle RTSWI will improve traffic safety at signalized intersection by means of reducing the driving stability risk

#### Backgrounds

##### 1 Importance of Speed Deviation

- Use of speed deviation as a surrogate for accidents
  - No accidents records (in preliminary road design level)
  - Often used in practice for evaluating the consistency of a geometry design
    - Criterion I and II (i.e., 10km/h deviation) is well recommended for transportation engineers in some Europe countries, Japan, Hungary, and Israel
- Road safety depends on the magnitude of speed deviation
  - Solomon (1964), Cirillo (1986)
    - The greater the deviation between average speed and operating speed of a driver the more chance of involvement in a crash
    - The lowest accident rate occurred within a speed range "15% to 20%" higher than the average speed
  - Recently, Gaber et al. (1989)
    - Crash rates increase with speed variance
  - Gaber et al. (2000)
    - Crash rate increases as the standard deviation of speed increases for all flow rates

#### Backgrounds



#### Backgrounds

##### 2 Ordered Response Probit Model

$$y_n^* = \beta' x_n + \varepsilon_n$$

$$y_n = \begin{cases} 1 & \text{if } -\infty \leq y_n^* \leq \mu_1 \quad (\text{Low driving stability risk}) \\ 2 & \text{if } \mu_1 < y_n^* \leq \mu_2 \quad (\text{Medium driving stability risk}) \\ 3 & \text{if } \mu_2 < y_n^* \leq \infty \quad (\text{High driving stability risk}) \end{cases}$$

$$\begin{aligned} P_n(y_n = 1) &= \Pr(y_n^* \leq \mu_1) = \Pr(\beta' x_n + \varepsilon_n \leq \mu_1) \\ &= \Pr(\varepsilon_n \leq \mu_1 - \beta' x_n) = \Phi(\mu_1 - \beta' x_n) = \Phi(-\beta' x_n) \\ P_n(y_n = 2) &= \Pr(\mu_1 < y_n^* \leq \mu_2) \\ &= \Pr(\mu_1 < \mu_2 - \beta' x_n) - \Pr(\mu_1 < \mu_1 - \beta' x_n) = \Phi(\mu_2 - \beta' x_n) - \Phi(-\beta' x_n) \\ P_n(y_n = 3) &= \Pr(\mu_2 < y_n^*) \\ &= 1 - \Phi(\mu_2 - \beta' x_n) \end{aligned}$$

$$L = \sum_{n=1}^N \sum_{j=1}^J \delta_{nj}^k \ln(P_n(y_n = k))$$

#### Data Collection

- Area & Time
  - November 21 (Tuesday) - 27 (Monday), 2006, Hiroshima City, Japan
- The west approach of Hiranobashi-higashi intersection
  - Signalized intersection approach with a limited traffic signal visibility
  - Bridge structure
  - Crest vertical alignment being a crest at 120m from stop-line
  - The most jeopardize signalized intersection in Hiroshima City




(i) General view of the approach

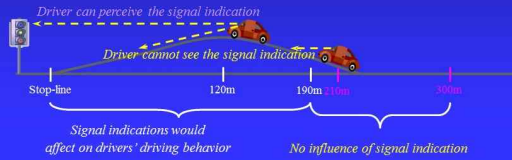


(ii) flow into the intersection from the approach

## Data Collection

### ■ Scenarios for the RTSWI provision

Scenario	Timing for provision	HMI pattern	Type	Static RTSWI	Dynamic RTSWI
1	no	no	Only voice	Attention! Traffic signal ahead	Attention! Stopping vehicle ahead
2	210m from the stop line	Only voice	Voice & Image		
3	210m from the stop line	Voice & image			
4	300m from the stop line	Only voice			
5	300m from the stop line	Voice & image			



## Data Collection

### ■ Experiment design

- Participants
  - 14 young drivers (13 Male, 1 Female) having a year more driving experience
  - Two drivers were allowed to driving a day
- Driving route
  - 7 intersections along 2-miles strength on "route 2" in Hiroshima City



Driving route "route 2"

## Data Collection

### ■ Apparatus

- GPS to support to gathering data by 0.1 sec
- HMI (Human Machine Interface) to provide voice and image information
- Cameras to tape a driver's face and the scene of jeopardize traffic situation
- HUD (Head-up Display) on windshield with the same level of drivers eyes
- Speed, de-/acceleration, lateral de-/acceleration, gap distance, brake pressure, de-/acceleration pressure, handling pressure, position of probe vehicle, etc.



(i) Probe vehicle



(ii) HUD Image

## Utility of In-vehicle RTSWI

### Importance of the Utility of in-vehicle RTSWI

#### ■ Effects of Traffic Safety Warning Information (TSWI)

- Carson et al. (2001) for ice-accident
- Al-Ghamdi et al. (2004) for camel-vehicle collision
- Charlton (2007) for countermeasures in horizontal curve
- Al-Ghamdi (2007) for fog warning system

#### ■ Utility of In-vehicle RTSWI

- *Provision of the TSWI might surely be valuable if drivers can easily understand, memorize, and use it for making a safe driving*
- Inversely, the value of the TSWI might be worthless, if drivers forget the information
- Same situation holds in provision of the in-vehicle RTSWI
- In this sense, it is reasonable to assume that there is a *strong relationship between the utility of the in-vehicle RTSWI and the memory of drivers*

## Utility of In-vehicle RTSWI

### Assumptions for the Utility of in-vehicle RTSWI

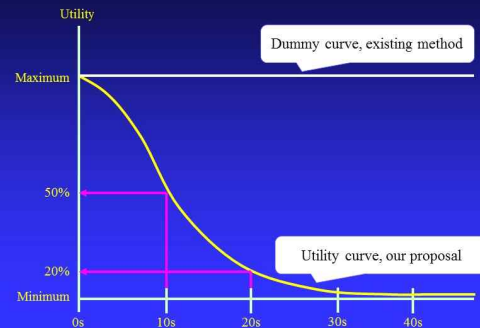
#### ■ Short-term memory (or working memory)

- Ogden (1995) - Lay (1986), Wickens (1984), Cumming (1964)
- Short term memory is requires *processing is temporarily stored*
- It has a *very limited capacity* and information is lost after *30s* unless it is actively reinforced by repetition or by use in some other activity
- Information cannot be recalled once it has faded
- Information in the short-term memory *fades if another task is interposed*

#### ■ Assumptions for the utility of in-vehicle RTSWI

- (A) Utility of the in-vehicle RTSWI reaches its *maximum (i.e. utility) at the time when provided to drivers*
- (B) Utility of the in-vehicle RTSWI *decrease over time after its provision*
- (C) Utility of the in-vehicle RTSWI *disappears after 30s of its provision*
- (D) *Minimum* utility of the in-vehicle RTSWI is approximate to *zero*

## Utility of In-vehicle RTSWI



## Utility of In-vehicle RTSWI

### Specification of Utility function of the in-vehicle RTSWI

#### ■ Candidate functions for utility of in-vehicle RTSWI

- Parameters were endogenously estimated from the data

$$U = -\kappa(t) \quad \text{Linear function with (-) slope}$$

$$U = -\phi(t^K) \quad K = 1, \Lambda, N \quad \text{Polynomial function with (-) slope}$$

$$U = \begin{cases} \exp(\gamma(t-t_0)) & \text{if } t \geq t_0 \\ 0 & \text{if } t < t_0 \end{cases} \quad \text{Exponential function}$$

$$U = \begin{cases} \frac{1}{\sqrt{v}} \exp(-\frac{1}{2} \frac{(t-t_0)^2}{v^2}) & \text{if } t \geq t_0 \\ 0 & \text{if } t < t_0 \end{cases} \quad \text{Normal density function}$$

## Driving Stability Risk Model Incorporating Short-Term Memory

### ■ Specification of a model build

- 4836 observations
- Non-stop behaviors
- Estimating the influence of the in-vehicle RTSWI on the driving stability risk
- Ordered response probit model

### ■ Employed variables

- Traffic operation factors
- Geometry factors
- Environmental factors
- Driver factors
- Provision of the in-vehicle RTSWI (dummy variable)
- Utility of the in-vehicle RTSWI (the normal density function)

### ■ Estimation

- Maximum Likelihood method
- TSP 5.0



Variables	Definition	mean	S.D.†
<b>Traffic operation factors</b>			
Speed difference	Absolute value of the difference between current speed and past speed [km/h]	0.169	0.251
Gap distance	Distance from the rear end of preceded vehicle to the front end of the probe vehicle divided by 1000 [m]	0.104	0.034
<b>Geometry factors</b>			
Signal visibility	Ability of drivers to see the traffic signal indication [0 = visibility (190m from the stop line); 1 = limited]	0.351	0.477
Vertical grades	Absolute value of vertical grades divided by 10 [%]	0.285	0.199
<b>Environment factors</b>			
Road surface	The condition of road surface when driving was performed on the subject road [0 = dry; 1 = wet]	0.432	0.495
Time slot	The time of day implementing the driving experiment during a day [0 = morning; 1 = afternoon]	0.491	0.500
Day slot	The day of recording the scenes either weekday or weekend [0 = weekday; 1 = weekend (holiday)]	0.589	0.492
<b>Driver factors</b>			
Trial number	The number of driving trials on the subject road during a day divided by 10 [integer, positive sign]	0.300	0.135
Driving experience	The real driving experience of each driver divided by 10 [integer, positive sign]	0.196	0.108
<b>Provision of in-vehicle RTSWI</b>			
Provision of the In-vehicle RTSWI	Provision of the in-vehicle RTSWI [0 = without; 1 = provision]	0.659	0.474
Utility of RTSWI	A value of in-vehicle RTSWI is assumed to follow the normal density function multiplied by 10 – without provision; 1 – provision	-	-

## Driving Stability Risk Model Incorporating Short-Term Memory

### ■ Elasticity

- All estimates (absolute value) are significantly less than one
- 1% change in continuous variable will lead to small change in the driving stability risk
- 1% increase in the gap distance between cars (or utility of in-vehicle RTSWI) will give a larger increase in the probability of low than that of vertical grade

### ■ Gap distance

- Needs to see car-following aspect

Continuous variables	Driving stability risk		
	low	medium	high
1% increase in speed difference	-0.080	0.005	0.088
<b>1% increase in gap distance</b>	<b>0.766</b>	<b>-0.048</b>	<b>-0.848</b>
1% increase in vertical grades	0.468	-0.030	-0.517
1% increase in trial number	-0.888	0.056	0.982
1% increase in driving experience	-0.365	0.023	0.404
<b>1% increase in utility RTSWI</b>	<b>0.470</b>	<b>-0.030</b>	<b>-0.519</b>

## Conclusions

### ■ Use of Ordered Response Probit (ORP) model

- It is an appropriate evaluation model for traffic safety using driving speeds in case of no traffic accident data
- Our proposal can be used for assessment of the effectiveness of ITS applications in terms of traffic safety analysis

### ■ Concept of Utility of in-vehicle RTSWI

- A type of exponential function can relax the assumptions for utility of in-vehicle RTSWI based on the characteristics of driver's short-term memory in driving condition
- Provision of in-vehicle RTSWI give a positive influence to traffic safety but its capacity is not long
- Elaborate analysis is possible compared to the existing method, which can produce more exact analysis results

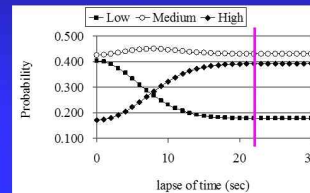
## ■ Estimation results

Variables	Existing method		Proposed method	
	Estimate	t-statistic	Estimate	t-statistic
Constant	0.913	10.982†	0.838	10.018†
Speed difference	0.400	4.381†	0.410	4.475†
<b>Gap distance</b>	<b>-7.443</b>	<b>-14.514†</b>	<b>-6.384</b>	<b>-11.928†</b>
Signal visibility	0.323	8.305†	0.412	10.808†
<b>Vertical grades</b>	<b>-1.173</b>	<b>-13.176†</b>	<b>-1.424</b>	<b>-15.517†</b>
<b>Road surface (wet)</b>	<b>-1.110</b>	<b>-26.888†</b>	<b>-1.050</b>	<b>-24.769†</b>
Time slot	0.250	4.846†	0.203	3.911†
Day slot	-	-	-	-
Trial number	1.902	9.596†	2.570	14.649†
Driving experience	1.328	8.005†	1.613	9.773†
<b>Provision of in-vehicle RTSWI</b>	<b>0.096</b>	<b>2.004*</b>	<b>-10.626</b>	<b>-10.699†</b>
<b>10</b> (for short-term memory)	-	-	39.092	8.349†
<b>24</b> (for driving stability risk model)	1.167	51.568†	1.196	51.423†
Observations	4836		4836	
Log-likelihood (LL) with zero coefficients	-5924.732		-5971.105	
Log-likelihood (LL) for estimated model	-4533.361		-4456.993	
<b>Adjusted R-squared</b>	<b>0.233</b>		<b>0.252</b>	
<b>Akaike's Information Criterion (AIC)</b>	<b>1.879</b>		<b>1.848</b>	

## Driving Stability Risk Model Incorporating Short-Term Memory

### ■ Probabilities of driving stability risk

- Sensitivity analysis was performed by controlling the utility of the in-vehicle RTSWI, while taking a value of zero for all discontinuous variables and average values for other continuous variables
- Low, medium, and high driving stability risk are 0.403, 0.426, and 0.171 when the in-vehicle RTSWI is provided. *These probabilities are changing until nearly 22 sec, and become a constant*, showing 0.178, 0.430, and 0.392 respectively



Thank You

## (참고 1) 충남연구원 - 계림전자기술대학교 교류협약서(MOU)

### 한국 충남연구원 - 중국 계림전자기술대학교

### 연구교류 및 협력 협약서

한국 충남연구원과 중국 계림전자기술대학교는 호혜평등의 원칙에 의거하여 지속적인 협력을 추진하기 위해 다음과 같은 협력사항을 추진하기로 협약한다.

**제1조 (목적)** 양 기관은 지역 및 도시 개발, 농업 농촌 등 다양한 분야에서 상호 발전을 위한 지속적인 교류에 힘쓴다.

#### 제2조 (협력분야)

1. 지역 교통 및 물류 등 지역개발, 농업 농촌 발전 등 다양한 분야에 대한 인적 교류
2. 공통관심사를 주제로 한 국제 학술세미나 공동 개최
3. 학술자료 및 정보 공유와 공동 조사연구
4. 기타 상호 교류 협력이 필요하다고 인정되는 사항

**제3조 (사업경비)** 이 협약의 이행에 필요한 인력과 자금투입은 각 기관이 스스로 부담함을 원칙으로 한다. 다만 필요시 협의에 의해 결정할 수 있다.

**제4조 (협약 효력 및 기간)** 본 협약 효력은 서명한 날로부터 발생한다. 협약의 유효기간은 체결일로부터 2년으로 하되, 별도의 서면 통보가 없는 한 매년 1년씩 자동 연장되는 것으로 한다.

**제5조 (기타)** 양 기관은 이 협약내용의 준수와 성실한 이행을 위해 서명하고 각 1부씩 보관한다.

2017년12월11일

한국 충남연구원

중국 계림전자기술대학교

국제교류학과

원장:

과장:

## (참고 2) MOU 및 계림전자기술대학교 방문 사진

